A Null Pointer Dereference Bug in OpenSSL (CVE-2014-0198)

```
\begin{split} \texttt{NPD}(b) &\triangleq \texttt{local} \ x_b, x_p \text{ in} \\ x_b &:= [b]; \\ \{\texttt{assume}(x_b = \texttt{null}); \texttt{setup\_write\_buffer}(b) \} + \{\texttt{assume}(x_b \neq \texttt{null}); \texttt{skip} \}; \\ \texttt{dispatch\_alert}(b) + \texttt{skip}; \\ x_p &:= [b]; \ L_{rp} \colon [x_p] \coloneqq 666 \end{split}
```

Fig. 9. The NPD program from OpenSSL adapted to the ISL language

We consider a null-pointer-dereference bug in OpenSSL, adapted to our ISL language as the NPD(b) program in Fig. 9. The NPD(b) program makes calls to the setup_write_buffer(b) and dispatch_alert(b) procedures, assumed to be inlined within NPD(b), as before. For brevity, we omit the code of these two procedures, and note that while setup_write_buffer(b) always ensures that the buffer at b is allocated, dispatch_alert(b) may accidentally deallocate the buffer at b and set it to null, causing a null-pointer-dereference error later. We thus assume the following specifications for these procedures:

$[b\mapsto e] extsf{setup_write_buffer}(b) \left[ok \colon \exists l_2. \ b\mapsto l_2*l_2\mapsto e ight]$	(NPD-SETUP)
$[b \mapsto l_2 * l_2 \mapsto -] \texttt{dispatch_alert}(b) [ok: b \mapsto \texttt{null} * l_2 \not\mapsto]$	(NPD-ALERT)

We can then prove the following error specifications for NPD(b):

$$[b \mapsto \text{null}] \text{ NPD}(b) [er(L_{rp}): \exists l_2. b \mapsto \text{null} * l_2 \not\mapsto]$$
(NPD-ER-1)

$$[b \mapsto l_2 * l_2 \mapsto -] \operatorname{NPD}(b) [er(\operatorname{L}_{rp}) : b \mapsto \operatorname{null} * l_2 \not\mapsto]$$
(NPD-ER-2)

(NPD-ER-1) describes the case where the buffer at b is originally unallocated and is subsequently allocated by setup_write_buffer(b), only to be deallocated by dispatch_alert(b) shortly after, causing a null-pointer-dereference error at L_{rp} . Analogously, (NPD-ER-2) describes the case where the buffer is initially allocated and later deallocated by dispatch_alert(b), causing an error at L_{rp} .

The proofs of (NPD-ER-1) and (NPD-ER-2) are straightforward. A proof sketch of (NPD-ER-1) is given in Fig. 10; the (NPD-ER-2) proof is analogous and omitted.

```
[b \mapsto \texttt{null}]
   local x_b, x_p in
       x_b := [b]; // (LOAD)
       [ok: x_b = \texttt{null} * b \mapsto \texttt{null}]
       { assume(x_b=null); // (ASSUME)
             [ok: x_b = \texttt{null} * b \mapsto \texttt{null}]
             setup_write_buffer(b); // (NPD-SETUP)
             [ok: x_b = \texttt{null} * \exists l_2.b \mapsto l_2 * l_2 \mapsto -]
       + \{...\}; // (CHOICE)
       [ok: x_b = \texttt{null} * \exists l_2. b \mapsto l_2 * l_2 \mapsto -]
           [ok:b\mapsto l_2*l_2\mapsto -]
           (dispatch_alert(b); // (NPD-ALERT)
           [ok: b \mapsto \texttt{null} * l_2 \not\mapsto ]
       [ok: x_b = \texttt{null} * \exists l_2. b \mapsto \texttt{null} * l_2 \not\mapsto ] // (EXIST, 4.2)
        +...); // (CHOICE)
       [ok: x_b = \texttt{null} * \exists l_2. b \mapsto \texttt{null} * l_2 \not\mapsto ]
       x_p := [b]; // (LOAD)
       [ok: x_b = x_p = \texttt{null} * \exists l_2. b \mapsto \texttt{null} * l_2 \not\mapsto ]
       L_{rp}: [x_p] := 666 // (STORENULL)
       [er(\mathbf{L}_{rp}): x_b = x_p = \texttt{null} * \exists l_2. \ b \mapsto \texttt{null} * l_2 \not\mapsto ]
       // (LOCAL, CONS)
[er(\mathbf{L}_{rp}): \exists l_2. \ b \mapsto \mathtt{null} * l_2 \not\mapsto ]
```

Fig. 10. A proof sketch of NPD-ER-1

B Soundness

Definition 1.

$$s_1 \sim_A s_2 \iff \forall x \in A. \ s_1(x) = s_2(x)$$

Proposition 1. For all assertions p and all s, s', h, if $(s, h) \in p$ and $s \sim_{fv(p)} s'$, then $(s', h) \in p$.

For all ϵ , \mathbb{C} , x, v, (s_1, h_1) and (s_2, h_2) , if $((s_1, h_1), (s_2, h_2)) \in [\mathbb{C}]$ and $x \notin fv(\mathbb{C})$, then $((s_1[x \mapsto v], h_1), (s_2[x \mapsto v], h_2)) \in [\mathbb{C}]$.

Lemma 1. For all $p, \mathbb{C}, q, \epsilon$, $if \vdash [p] \mathbb{C} [\epsilon : q]$ holds, then:

$$\begin{array}{l} \forall (s_q, h_q) \in q. \; \forall h. \; h_q \; \# \; h \implies \\ \exists (s_p, h_p) \in p. \; s_p \sim_{\overline{\mathsf{mod}}(\mathbb{C})} s_q \land \left((s_p, h_p \uplus h), (s_q, h_q \uplus h) \right) \in \llbracket \mathbb{C} \rrbracket \epsilon \end{array}$$

where $h_q \# h \iff dom(h_q) \cap dom(h) = \emptyset$ denotes that h_q and h are compatible in that their composition is defined.

Proof. We proceed by induction on the structure of incorrectness triples. In what follows we write h_0 to denote an empty heap (i.e., $dom(h_0) = \emptyset$).

Case Skip

Pick an arbitrary $\sigma_q = (s, h_q) \in \text{emp}$ and an arbitrary h such that $h_q \# h$. It then suffices to show that $((s, h_q \uplus h), (s, h_q \uplus h)) \in [[\texttt{skip}]]ok$, which follows from the semantics of skip immediately.

Case Assign

Pick an arbitrary x, e, h and $(s_q, h_q) \in q$ such that $h_q \uplus h$. We then know $h_q = h_0$ and $s_q(x) = s_q(e[x'/x])$. Let $s_p = s_q[x \mapsto s_q(x')]$. By definition we then know that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_p, h_q) \in p$. It then suffices to show that $((s_p, h_q \uplus h), (s_q, h_q \uplus h)) \in [x := e] ok$, which follows from the semantics of x := e immediately.

The proof of HAVOC is analogous and omitted here.

Case LOAD

Pick an arbitrary x, y and $(s_q, h_q) \in q$. Pick an arbitrary h such that $h_q \# h$. We then know there exist l, v such that $s_q(x) = s_q(e[x'/x]) = v$, $s_q(y) = l$ and $h_q \triangleq [l \mapsto v]$. Let $s_p \triangleq s_q[x \mapsto s_q(x')]$. By definition we then know that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_p, h_q) \in p$. It then suffices to show $((s_p, h_q \uplus h), (s_q, h_q \uplus h)) \in [x := [y]] ok$, which follows from the semantics of x := [y] immediately.

Case LOADER

Pick an arbitrary x, y and $(s_q, h_q) \in q$. Pick an arbitrary h such that $h_q \# h$. We then know there exist l such that $s_q(y)=l$ and $h_q \triangleq [l \mapsto \bot]$. By definition we then know that $s_q \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_q, h_q) \in p$. It then suffices to show $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [x := [y]]er(L)$, which follows from the semantics of x := [y] immediately.

Case LOADNULL

Pick an arbitrary x, y and $(s_q, h_q) \in q$. Pick an arbitrary h such that $h_q \# h$. We then know $h_q = h_0$ and $s_q(y) =$ **null**. By definition we then know that $s_q \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_q, h_q) \in p$. It then suffices to show $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [x := [y]]er(L)$, which follows from the semantics of x := [y] immediately.

The proofs of the STORE, STOREER and STORENULL cases are analogous to those of LOAD, LOADER and LOADNULL respectively, and are omitted here.

Case Alloc1

Pick an arbitrary x and $(s_q, h_q) \in q$. We then know there exists l and $v \in VAL$ such that $s_q(x) = l$ and $h_q \triangleq [l \mapsto v]$. Pick an arbitrary h such that $h_q \# h$. Let $s_p \triangleq s_q[x \mapsto s_q(x')], h_p = h_0$. By definition we then know that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_p, h_p) \in p$. Since $h_q \# h$ and $dom(h_p) \subseteq dom(h_q)$, from the definition of \boxplus we also know that $h_p \# h$. It then suffices to show that $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [x:=\texttt{alloc}()]ok$, which follows from the semantics of x:=alloc().

Case Alloc2

Pick an arbitrary x, y and $(s_q, h_q) \in q$. We then know there exists l and $v \in VAL$ such that $s_q(x)=s_q(y)=l$ and $h_q \triangleq [l \mapsto v]$. Pick an arbitrary h such that $h_q \# h$. Let $s_p \triangleq s_q[x \mapsto s_q(x')], h_p=[l \mapsto \bot]$. By definition we then know that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_p, h_p) \in p$. Since $h_q \# h$ and $dom(h_p)=dom(h_q)$, from the definition of \exists we also know that $h_p \# h$. It then suffices to show that $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [x:=\texttt{alloc}()]ok$, which follows from the semantics of x:=alloc().

Case Free

Pick an arbitrary x and $(s_q, h_q) \in q$. We then know there exists l such that $s_q(x)=l$ and $h_q \triangleq [l \mapsto \bot]$. Pick an arbitrary h such that $h_q \# h$. Let $h_p=[l \mapsto s_q(e)]$. By definition we then know that $s_q \sim_{\mathsf{mod}(\mathbb{C})} s_q$ and $(s_q, h_p) \in p$. Since $h_q \# h$ and $dom(h_p)=dom(h_q)$, from the definition of \uplus we also know that $h_p \# h$. It then suffices to show that $((s_q, h_p \uplus h), (s_q, h_q \uplus h)) \in [[\texttt{free}(x)]]ok$, which follows from the semantics of free(x) immediately.

Case FreeEr

Pick an arbitrary x and $(s_q, h_q) \in q$. We then know there exists l such that $s_q(x) = l$ and $h_q \triangleq [l \mapsto \bot]$. Pick an arbitrary h such that $h_q \# h$. By definition we then know that $s_q \sim_{\overline{\mathsf{mod}}(\mathbb{C})} s_q$. It then suffices to show that $((s_q, h_q \boxplus h), (s_q, h_q \boxplus h)) \in$ [[free(x)][er(L)], which follows from the semantics of free(x) immediately.

Case FreeNull

Pick an arbitrary x and $(s_q, h_q) \in q$. We then know $h_q = h_0$ and $s_q(x) =$ null. Pick an arbitrary h such that $h_q \# h$. By definition we then know that $s_q \sim_{\mathsf{mod}(\mathbb{C})} s_q$. It then suffices to show that $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [[free(x)]]er(L)$, which follows from the semantics of free(x) immediately.

Case Error

Pick an arbitrary $(s_q, h_q) \in q$. We then know that $h_q \triangleq h_0$. Pick an arbitrary h such that $h_q \# h$. As $(s_q, h_q) \in q$, it then suffices to show that $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [[error]]er(L)$, which follows from the semantics of error immediately.

Case Assume

Pick an arbitrary $(s_q, h_q) \in q$. We then know that $s_q(B) \neq 0$. Pick an arbitrary h such that $h_q \# h$. Since $q = p \land B$ and $(s_q, h_q) \in q$, we also have $(s_q, h_q) \in p$. By definition we know that $s_q \sim_{\overline{\mathsf{mod}}(\mathbb{C})} s_q$. It thus suffices to show that $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [[\texttt{assume}(B)]]ok$, which follows from the semantics of assume(B) immediately.

Case Local

Pick an arbitrary x, h and $(s_q, h_q) \in \exists x. q$ such that $h_q \notin h$. From the semantics of assertions we then know that there exists v and s'_q such that $s'_q = s_q[x \mapsto v]$ and $(s'_q, h_q) \in q$. Since from the premise of LOCAL we have $[p] \ \mathbb{C} \ [\epsilon : q]$, from the inductive hypothesis we know there exist s'_p, h_p such that $s'_p \sim_{\mathsf{mod}(\mathbb{C})} s'_q$, $(s'_p, h_p) \in p$ and $((s'_p, h_p \uplus h), (s'_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$. Let $s_p = s'_p[x \mapsto s_q(x)]$. Note that since $s_p[x \mapsto s'_p(x)] = s'_p$ and $(s'_p, h_p) \in p$, from the semantics of assertions we have $(s_p, h_p) \in \exists x. p$. On the other hand, since $s_p(x) = s_q(x)$ and $((s'_p, h_p \uplus h), (s'_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$, from the definitions of $[\![.]\!], s_p, s'_p, s_q$ and s'_q we also have $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\![\texttt{local } x \text{ in } \mathbb{C}]\!] \epsilon$. Moreover, since $s'_p \sim_{\overline{\mathsf{mod}(\mathbb{C})}} s'_q$ and $s_p = s'_p[x \mapsto s_q(x)]$ and thus $s_q(x) = s_p(x)$, we also have $s_p \sim_{\overline{\mathsf{mod}(\mathsf{local } x \text{ in } \mathbb{C})} s_q$, as required.

Case EXIST

Pick an arbitrary x, h and $(s_q, h_q) \in \exists x. q$ such that $h_q \# h$. From the semantics of assertions we then know that there exists v and s'_q such that $s'_q = s_q[x \mapsto v]$ and $(s'_q, h_q) \in q$. Since from the premise of EXIST we have $[p] \mathbb{C} [\epsilon : q]$, from the inductive hypothesis we know there exist s'_p, h_p such that $s'_p \sim_{\mathsf{mod}(\mathbb{C})} s'_q$, $(s'_p, h_p) \in p$ and $((s'_p, h_p \uplus h), (s'_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$. Let $s_p = s'_p[x \mapsto s_q(x)]$. Note that since $s_p[x \mapsto s'_p(x)] = s'_p$ and $(s'_p, h_p) \in p$, from the semantics of assertions we have $(s_p, h_p) \in \exists x. p$. On the other hand, since $s_p(x) = s_q(x)$ and $((s'_p, h_p \uplus h), (s'_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$, and since $x \notin \mathsf{fv}(\mathbb{C})$, from Proposition 1 and the definitions of s_p, s'_p, s_q and s'_q we also have $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$. Moreover, since $s'_p \sim_{\overline{\mathsf{mod}(\mathbb{C})}} s'_q$ and $s_p = s'_p[x \mapsto s_q(x)]$ and thus $s_q(x) = s_p(x)$, from the definitions of s_p, s'_p, s_q and s'_q we also have $s_p \sim_{\overline{\mathsf{mod}(\mathbb{C})}} s_q$, as required.

Case SEQ1

Pick an arbitrary $(s_q, h_q) \in q$ and h such that $h_q \# h$. Since from the premise of SEQ1 we have $[p] \mathbb{C} [\epsilon : q]$ with $\epsilon \neq ok$, from the inductive hypothesis we know there exist s_p, h_p such that $s_p \sim_{\overline{\mathsf{mod}}(\mathbb{C}_1)} s_q, (s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in$

 $\llbracket \mathbb{C}_1 \rrbracket \epsilon$. As such, since $\mathsf{mod}(\mathbb{C}_1) \subseteq \mathsf{mod}(\mathbb{C}_1; \mathbb{C}_2)$, we know $s_p \sim_{\mathsf{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_q$, $(s_p, h_p) \in p$ and from the semantics of $\mathbb{C}_1; \mathbb{C}_2$ we have $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in \llbracket \mathbb{C}_1; \mathbb{C}_2 \rrbracket \epsilon$, as required.

Case SEQ2

Pick arbitrary $(s_q, h_q) \in q$ and h such that $h_q \# h$. As from the second premise of SEQ2 we have $[r] \mathbb{C}_2 [\epsilon : q]$ and $\operatorname{mod}(\mathbb{C}_2) \subseteq \operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)$, from the inductive hypothesis we know there exist s_r, h_r such that $s_r \sim_{\operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_q$, $(s_r, h_r) \in r$ and $((s_r, h_r \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}_2]\epsilon$. Moreover, as from the first premise we have $[p] \mathbb{C}_1 [ok : r]$ and $\operatorname{mod}(\mathbb{C}_1) \subseteq \operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)$, from the inductive hypothesis we know there exist s_p, h_p such that $s_p \sim_{\operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_r$, $(s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_r, h_r \uplus h)) \in [\mathbb{C}_1] ok$. As such, since $s_p \sim_{\operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_r$, $s_r \sim_{\operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_q$ we know $s_p \sim_{\operatorname{mod}(\mathbb{C}_1; \mathbb{C}_2)} s_q$, $(s_p, h_p) \in p$ and from the semantics of $\mathbb{C}_1; \mathbb{C}_2$ we have $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}_1; \mathbb{C}_2]\epsilon$, as required.

Case CHOICE

Pick arbitrary $(s_q, h_q) \in q$ and h such that $h_q \# h$. From the premise of CHOICE we know there exists $i \in \{1, 2\}$ such that $[p] \mathbb{C}_i [\epsilon : q]$. As such, from the inductive hypothesis we know there exist s_p, h_p such that $s_p \sim_{\overline{\mathsf{mod}}(\mathbb{C}_i)} s_q, (s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}_i] \epsilon$. As such, since $\mathsf{mod}(\mathbb{C}_i) \subseteq \mathsf{mod}(\mathbb{C}_1 + \mathbb{C}_2)$, we know $s_p \sim_{\overline{\mathsf{mod}}(\mathbb{C}_1 + \mathbb{C}_2)} s_q, (s_p, h_p) \in p$ and from the semantics of $\mathbb{C}_1 + \mathbb{C}_2$ we have $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}_1 + \mathbb{C}_2] \epsilon$, as required.

Case Loop1

Pick an arbitrary $(s_q, h_q) \in q$ and an arbitrary h such that $h_q \# h$. It then suffices to show that $((s_q, h_q \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}^*] ok$, which follows from the semantics of \mathbb{C}^* immediately.

Case LOOP2

Pick arbitrary $(s_q, h_q) \in q$ and h such that $h_q \# h$. From the premise of LOOP2 we have $[p] \mathbb{C}^*; \mathbb{C} [\epsilon : q]$ and thus from the inductive hypothesis we know there exists s_p, h_p such that $s_p \sim_{\mathsf{mod}(\mathbb{C};\mathbb{C}^*)} s_q, (s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}^*; \mathbb{C}]] \epsilon$. Moreover, by definition we have $\mathsf{mod}(\mathbb{C}^*; \mathbb{C}) = \mathsf{mod}(\mathbb{C}^*)$. On the other hand, it is straightforward to show that $[\mathbb{C}^*; \mathbb{C}]] = \bigcup_{i \in \mathbb{N}^+} [\mathbb{C}^i]$ and thus $[\mathbb{C}^*; \mathbb{C}]] \subseteq [\mathbb{C}^*]$. Consequently, we know there exists s_p, h_p such that $s_p \sim_{\mathsf{mod}(\mathbb{C}^*)} s_q$, $(s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}^*]\epsilon$, as required.

Case Cons

Pick arbitrary $(s_q, h_q) \in q$ and h such that $h_q \# h$. As form the premise of CONS we have $q \Rightarrow q'$, we also know that $(s_q, h_q) \in q'$. On the other hand, from the premise of CONS we have $[p'] \mathbb{C} [\epsilon : q']$ and thus from the inductive hypothesis we know there exist s_p, h_p such that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q, (s_p, h_p) \in p'$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}]\epsilon$. Moreover, as $p' \Rightarrow p$ and $(s_p, h_p) \in p'$ we also

33

have $(s_p, h_p) \in p$. That is, we know there exists s_p, h_p such that $s_p \sim_{\overline{\mathsf{mod}}(\mathbb{C})} s_q$, $(s_p, h_p) \in p$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}]\epsilon$, as required.

Case 4.2

Pick arbitrary $(s_2, h_2) \in q * r$ and h such that $h_2 \# h$. From the definition of * we then know there exists h_q, h_r such that $(s_2, h_q) \in q$, $(s_2, h_r) \in r$ and $h_2 \triangleq h_q \boxplus h_r$. From the definition of # and \boxplus we then also have $h_q \# h_r \boxplus h$. On the other hand, from the premise of 4.2 we have $[p] \mathbb{C} [\epsilon : q]$ and thus from the inductive hypothesis we know there exists s_1, h_p such that $s_1 \sim_{\mathsf{mod}(\mathbb{C})} s_2, (s_1, h_p) \in p$ and $((s_1, h_p \boxplus h_r \boxplus h), (s_q, h_q \boxplus h_r \boxplus h)) \in [\mathbb{C}] \epsilon$. Moreover, since $s_1 \sim_{\mathsf{mod}(\mathbb{C})} s_2$ and as from the premise of 4.2 we have $\mathsf{mod}(\mathbb{C}) \cap \mathsf{fv}(r) = \emptyset$, we also have $s_1 \sim_{\mathsf{fv}(r)} s_2$. Consequently, since $(s_2, h_r) \in r$, from Proposition 1 we have $(s_1, h_r) \in r$. As such from the definition of * we have $(s_1, h_p \boxplus h_r) \in p * r$. That is, we know there exists s_1 and $h_1 = h_p \boxplus h_r$ such that $s_1 \sim_{\mathsf{mod}(\mathbb{C})} s_2, (s_1, h_1) \in p * r$ and $((s_1, h_1 \boxplus h), (s_q, h_2 \boxplus h)) \in [\mathbb{C}] \epsilon$, as required.

Case DISJ

Pick arbitrary $(s_q, h_q) \in q_1 \lor q_2$ and h such that $h_q \# h$. We then know there exists $i \in \{1, 2\}$ such that $(s_q, h_q) \in q_i$. From the premise of DISJ we have $[p_i] \mathbb{C}$ $[\epsilon : q_i]$ and thus from the inductive hypothesis we know there exists s_p, h_p such that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q, (s_p, h_p) \in p_i$ and $((s_p, h_p \uplus h), (s_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$. Moreover, since $p_i \subseteq p_1 \lor p_2$ and $(s_p, h_p) \in p_i$, we also have $(s_p, h_p) \in p_1 \lor p_2$. That is, we know there exists s_p, h_p such that $s_p \sim_{\mathsf{mod}(\mathbb{C})} s_q, (s_q, h_q \uplus h)) \in [\mathbb{C}] \epsilon$, as required.

Theorem 4 (Soundness). For all $p, \mathbb{C}, q, \epsilon$, $if \vdash [p] \mathbb{C} [\epsilon : q]$ holds, then $\models [p] \mathbb{C} [\epsilon : q]$ also holds.

Proof. Pick arbitrary $p, \mathbb{C}, q, \epsilon$ such that $\vdash [p] \mathbb{C} [\epsilon : q]$ holds. Pick an arbitrary $(s_q, h_q) \in q$. It then suffices to show there exists $(s_p, h_p) \in p$ such that $((s_p, h_p), (s_q, h_q)) \in [\mathbb{C}] \epsilon$.

From the definition of \boxplus and # we then know that $h_q \# h_0$. As such, from Lemma 1 we know there exists $(s_p, h_p) \in p$ such that $((s_p, h_p \uplus h_0), (s_q, h_q \uplus h_0)) \in$ $[\mathbb{C}]\epsilon$. That is, there exists $(s_p, h_p) \in p$ such that $((s_p, h_p), (s_q, h_q)) \in [\mathbb{C}]\epsilon$, as required.

foot (.) : COMM \rightarrow EXIT $\rightarrow \mathcal{P}(\text{STATE} \times \text{STATE})$ foot (skip) $\epsilon \triangleq \{((s, h_0), (s, h_0)) \mid s \in \text{STORE}\}$ foot (x := e) $ok \triangleq \{((s, h_0), (s[x \mapsto s(e)], h_0)) \mid s \in \text{STORE}\}$ foot (x := e) $er(-) \triangleq \emptyset$ foot (x := *) $ok \triangleq \{((s, h_0), (s[x \mapsto v], h_0)) \mid v \in VAL\}$ foot (x := *) $er(-) \triangleq \emptyset$ foot (assume(B)) $ok \triangleq \{(\sigma, \sigma) \mid \sigma = (s, h_0) \land s(B) \neq 0\}$ foot (assume(B)) $er(-) \triangleq \emptyset$ $\texttt{foot}(\texttt{local} \ x \ \texttt{in} \ \mathbb{C}) \ \epsilon \triangleq \left\{ ((s[x \mapsto v], h), (s'[x \mapsto v], h')) \left| \begin{array}{c} ((s, h), (s', h')) \in \texttt{foot}(\mathbb{C}) \ \epsilon \\ \land v \in \mathsf{VAL} \end{array} \right\}$ foot (L: error) $ok \triangleq \emptyset$ foot (L: error) $er(L') \triangleq \{((\sigma, \sigma) \mid \sigma = (s, h_0) \land L = L'\}$ $\texttt{foot}(\mathbb{C}_1;\mathbb{C}_2) \epsilon \triangleq \{(\sigma,\sigma') \mid \epsilon \neq ok \land (\sigma,\sigma') \in \texttt{foot}(\mathbb{C}_1) \epsilon \}$ $\cup \left\{ (\sigma_1 \bullet \sigma, \sigma_2 \bullet \sigma') \, \middle| \begin{array}{l} \exists \sigma_c. \ (\sigma_1, \sigma' \bullet \sigma_c) \in \texttt{foot} \left(\mathbb{C}_1\right) ok \\ \land \ (\sigma_c \bullet \sigma, \sigma_2) \in \texttt{foot} \left(\mathbb{C}_2\right) \epsilon \end{array} \right\}$ foot $(\mathbb{C}_1 + \mathbb{C}_2) \epsilon \triangleq$ foot $(\mathbb{C}_1) \epsilon \cup$ foot $(\mathbb{C}_2) \epsilon$ $\texttt{foot}\left(\mathbb{C}^{\star}\right)\epsilon \triangleq \left\{\left((s,h_{0}),(s,h_{0})\right) \middle| \epsilon = ok\right\} \cup \bigcup_{i \in \mathbb{N}^{d}} \texttt{foot}\left(\mathbb{C}^{i}\right)\epsilon$ $\texttt{foot}(x:=\texttt{alloc}()) ok \triangleq \{((s,h), (s[x \mapsto l], [l \mapsto v])) \mid v \in \text{VAL} \land (h=h_0 \lor h=[l \mapsto \bot]\}$ foot (x := alloc()) $er(-) \triangleq \emptyset$ foot (L: free(x)) $ok \triangleq \{((s, [l \mapsto v]), (s, [l \mapsto \bot])) \mid s(x) = l \land v \in VAL\}$ $\texttt{foot}\left(\texttt{L}:\texttt{free}(x)\right)er(\texttt{L}') \triangleq \left\{\left((s,[l\mapsto \bot]),(s,[l\mapsto \bot])\right) \mid \texttt{L}=\texttt{L}' \land s(x)=l\right\}$ $\cup \left\{ \left((s, h_0), (s, h_0) \right) \mid L = L' \land s(x) = \texttt{null} \right\}$ foot (L: x := [y]) $ok \triangleq \{((s, [l \mapsto v]), (s[x \mapsto v], [l \mapsto v])) \mid s(y) = l\}$ $\texttt{foot} (\texttt{L}: x := [y]) \ er(\texttt{L}') \triangleq \left\{ \left((s, [l \mapsto \bot]), (s, [l \mapsto \bot]) \right) \mid \texttt{L} = \texttt{L}' \land s(y) = l \right\}$ $\cup \left\{ \left((s, h_0), (s, h_0) \right) \mid L = L' \land s(y) = \texttt{null} \right\}$ foot (L: [x] := y) $ok \triangleq \{ ((s, [l \mapsto v]), (s, [l \mapsto s(y)])) \mid s(x) = l \land v \in VAL \} \}$ foot (L: [x] := y) $er(L') \triangleq \{((s, [l \mapsto \bot]), (s, [l \mapsto \bot])) \mid L = L' \land s(x) = l\}$ $\cup \left\{ \left((s, h_0), (s, h_0) \right) \mid L = L' \land s(x) = \texttt{null} \right\}$

Fig. 11. The local ISL footprints where h_0 denotes an empty heap $(dom(h_0)=\emptyset)$

C Footprints

ISL Footprints The definition of ISL footprints is given in Fig. 11. Note that the definitions of $\texttt{foot}_{SL}(\mathbb{C})$ and $\texttt{foot}(\mathbb{C})$ ok agree for all \mathbb{C} with the exception of $\mathbb{C}=x:=\texttt{alloc}()$ and $\mathbb{C}=\texttt{free}(x)$. In the case of $\mathbb{C}=x:=\texttt{alloc}()$ this is because $\texttt{foot}(\mathbb{C})$ additionally allows allocation from a singleton heap with a deallocated

location. In the case of $\mathbb{C}=\texttt{free}(x)$ this is because $\texttt{foot}(\mathbb{C})$ simply mutates the location at x to record \perp and does not remove it from the heap.

It is straightforward to demonstrate that the footprint of a program is included in its semantics, as captured by the following lemma.

Lemma 2. For all $\mathbb{C} \in \text{COMM}$ and $\epsilon \in \text{EXIT}$: foot $(\mathbb{C}) \epsilon \subseteq \llbracket \mathbb{C} \rrbracket \epsilon$.

Proof. Follows by straightforward induction on the structure of \mathbb{C} .

We next proceed with several auxiliary lemmas and then prove our footprint theorem (Theorem 5).

Lemma 3 (Cross-split property). For all $h_1, h_2, h_3, h_4 \in \text{HEAP}$:

 $h_1 \uplus h_2 = h_3 \uplus h_4 \Rightarrow \exists h_{13}, h_{14}, h_{23}, h_{24}. \ h_1 = h_{13} \uplus h_{14} \land h_2 = h_{23} \uplus h_{24} \land h_3 = h_{13} \uplus h_{23} \land h_4 = h_{14} \uplus h_{24}$

Proof. Follows from the definition of \uplus on heaps.

Lemma 4 (Heap Monotonicity). For all $s_1, s_2, h, h_1, h_2, \mathbb{C}, \epsilon, if((s_1, h_1), (s_2, h_2)) \in [\mathbb{C}] \epsilon$ and $h_2 \# h$, then $((s_1, h_1 \uplus h), (s_2, h_2 \uplus h)) \in [\mathbb{C}] \epsilon$.

Proof. Follows by straightforward induction on the structure of \mathbb{C} .

Corollary 1. For all $s_1, s_2, h, h_1, h_2, \mathbb{C}, \epsilon$, if $((s_1, h_1), (s_2, h_2)) \in \text{foot}(\mathbb{C}) \epsilon$ and $h_2 \# h$, then $((s_1, h_1 \uplus h), (s_2, h_2 \uplus h)) \in \llbracket \mathbb{C} \rrbracket \epsilon$.

Proof. Follows immediately from Lemma 2 and Lemma 4.

Theorem 5. For all $\mathbb{C} \in \text{COMM}$ and $\epsilon \in \text{EXIT}$: $[\![\mathbb{C}]\!]\epsilon = \text{frame}(\text{foot}(\mathbb{C})\epsilon)$.

Proof. By induction on the structure of \mathbb{C} .

 $\mathbf{Case}\ \mathbb{C} = \mathtt{skip}$

There are two cases to consider: 1) $\epsilon = er(L')$ for some L'; or 2) $\epsilon = ok$. In case (1) by definition we have $\llbracket \mathbb{C} \rrbracket \epsilon = \emptyset = \texttt{frame}$ (foot (\mathbb{C}) ϵ), as required. In case (2), from the definitions of foot (.), frame (.) and \llbracket . \rrbracket we have $\llbracket \mathbb{C} \rrbracket \epsilon = \{(\sigma, \sigma) \mid \sigma \in \texttt{STATE}\} = \{((s, h_0 \uplus h), (s, h_0 \uplus h)) \mid h \in \texttt{HEAP}\} = \texttt{frame}$ (foot (\mathbb{C}) ϵ), as required.

Case $\mathbb{C} = x := e$

There are two cases to consider: 1) $\epsilon = er(L')$ for some L'; or 2) $\epsilon = ok$. In case (1) by definition we have $[\mathbb{C}]\epsilon = \emptyset = \texttt{frame}(\texttt{foot}(\mathbb{C})\epsilon)$, as required. In case (2) from the definitions of foot(.), frame(.) and [.] we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ \left((s,h), (s[x \mapsto s(e)],h) \right) \middle| (s,h) \in \text{STATE} \right\} \\ &= \left\{ \left((s,h_0 \uplus h), (s[x \mapsto s(e)],h_0 \uplus h) \right) \middle| h \in \text{HEAP} \right\} \\ &= \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}\right) \epsilon\right) \end{split}$$

Case $\mathbb{C} = x := *$

The proof of this case is analogous to that of the previous case and is omitted.

Case $\mathbb{C} = L: x := [y]$

There are three cases to consider: 1) $\epsilon = ok$; or 2) $\epsilon = er(L)$; or 3) $\epsilon = er(L')$ for some $L' \neq L$. In case (1) from the definitions of foot (.), frame (.) and [].] we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ ((s,h), (s[x \mapsto v],h)) \, \middle| \, h(s(y)) = v \in \text{VAL} \right\} \\ &= \left\{ ((s,[l \mapsto v] \uplus h), (s[x \mapsto v],[l \mapsto v] \uplus h)) \, \middle| \, v \in \text{VAL} \land s(y) = l \land h \in \text{HEAP} \right\} \\ &= \texttt{frame} \left(\texttt{foot} (\mathbb{C}) \epsilon \right) \end{split}$$

Similarly, in case (2) we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ ((s,h),(s,h)) \, \middle| \, h(s(y)) = \bot \right\} \\ &= \left\{ ((s,[l \mapsto \bot] \uplus h),(s,[l \mapsto \bot] \uplus h)) \, \middle| \, s(y) = l \land h \in \mathrm{HEAP} \right\} \\ &= \mathtt{frame} \left(\mathtt{foot} \left(\mathbb{C} \right) \epsilon \right) \end{split}$$

Finally, in case (3) we have $\llbracket \mathbb{C} \rrbracket \epsilon = \emptyset = \texttt{frame}(\texttt{foot}(\mathbb{C})\epsilon)$, as required.

Case $\mathbb{C} = L: [x] := y$

The proof of this case is analogous to that of the previous case and is omitted.

Case $\mathbb{C} = x := \texttt{alloc()}$

There are two cases to consider: 1) $\epsilon = er(\mathbf{L}')$ for some \mathbf{L}' ; or 2) $\epsilon = ok$. In case (1) by definition we have $[\mathbb{C}]\epsilon = \emptyset = \texttt{frame}(\texttt{foot}(\mathbb{C})\epsilon)$, as required. In case (2) from the definitions of foot(.), frame(.) and [.] we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ ((s,h), (s[x \mapsto l], h[l \mapsto v])) \, \middle| \, v \in \text{VAL} \land (l \notin dom(h) \lor h(l) = \bot) \right\} \\ &= \left\{ ((s,h \uplus h'), (s[x \mapsto l], [l \mapsto v] \uplus h')) \, \middle| \begin{array}{l} v \in \text{VAL} \land (h = h_0 \lor h = [l \mapsto \bot]) \\ \land h' \in \text{HEAP} \end{array} \right\} \\ &= \texttt{frame} \left(\texttt{foot} \left(\mathbb{C} \right) \epsilon \right) \end{split}$$

Case $\mathbb{C} = \texttt{free}(x)$

There are three cases to consider: 1) $\epsilon = ok$; or 2) $\epsilon = er(L)$; or 3) $\epsilon = er(L')$ for some $L' \neq L$. In case (1) from the definitions of foot (.), frame (.) and [].] we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ ((s,h), (s,h[l \mapsto \bot])) \, \middle| \, s(x) = l \land h(l) \in \mathrm{VAL} \right\} \\ &= \left\{ ((s,[l \mapsto v] \uplus h), (s,[l \mapsto \bot] \uplus h)) \, \middle| \, s(x) = l \land v \in \mathrm{VAL} \land h \in \mathrm{HEAP} \right\} \\ &= \mathtt{frame} \left(\mathtt{foot} \left(\mathbb{C} \right) \epsilon \right) \end{split}$$

Similarly, in case (2) we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ ((s,h),(s,h)) \, \middle| \, s(x) = l \land h(l) = \bot \right\} \\ &= \left\{ ((s,[l \mapsto \bot] \uplus h),(s,[l \mapsto \bot] \uplus h)) \, \middle| \, s(x) = l \land h \in \mathrm{HEAP} \right\} \\ &= \mathtt{frame} \left(\mathtt{foot} \left(\mathbb{C} \right) \epsilon \right) \end{split}$$

Finally, in case (3) we have $\llbracket \mathbb{C} \rrbracket \epsilon = \emptyset = \texttt{frame} (\texttt{foot} (\mathbb{C}) \epsilon)$, as required.

$\mathbf{Case}\ \mathbb{C}=\mathtt{L}{:}\,\mathtt{error}$

There are three cases to consider: 1) $\epsilon = ok$; or 2) $\epsilon = er(L')$ for $L' \neq L$; or 3) $\epsilon = er(L)$. In (1) and (2) by definition we have $[\mathbb{C}]\epsilon = \emptyset = \texttt{frame}(\texttt{foot}(\mathbb{C})\epsilon)$, as

required. In (3) from the definitions of foot (.), frame (.) and [[.]] we have $[\mathbb{C}]]\epsilon = \{(\sigma, \sigma) | \sigma \in \text{STATE}\} = \{((s, h_0 \uplus h), (s, h_0 \uplus h)) | h \in \text{HEAP}\} = \text{frame} (\text{foot} (\mathbb{C}) \epsilon),$ as required.

Case $\mathbb{C} = \operatorname{assume}(B)$

There are two cases to consider: 1) $\epsilon = er(L')$ for some L'; or 2) $\epsilon = ok$. In case (1) by definition we have $[\mathbb{C}]\epsilon = \emptyset = \texttt{frame}(\texttt{foot}(\mathbb{C})\epsilon)$, as required. In case (2) from the definitions of \texttt{foot}(.), \texttt{frame}(.) and [..] we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \left\{ \left((s,h), (s,h) \right) \, \middle| \, s(B) \neq 0 \right\} \\ &= \left\{ \left((s,h_0 \uplus h), (s,h_0 \uplus h) \right) \, \middle| \, s(B) \neq 0 \land h \in \text{HEAP} \right\} \\ &= \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}\right) \epsilon\right) \end{split}$$

 $\mathbf{Case}\ \mathbb{C} = \texttt{local}\ x \text{ in } \mathbb{C}'$

$$\forall \epsilon. \, [\![\mathbb{C}']\!] \epsilon = \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}' \right) \epsilon \right) \tag{I.H}$$

From the definitions of foot(.), frame(.), $[\![.]\!]$ and (I.H) we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &\triangleq \left\{ \left((s[x \mapsto v], h), (s'[x \mapsto v], h') \right) \left| \begin{array}{c} ((s, h), (s', h')) \in \llbracket \mathbb{C}' \rrbracket \epsilon \right\} \\ &\stackrel{(\mathrm{I.H})}{=} \left\{ \left((s[x \mapsto v], h), (s'[x \mapsto v], h') \right) \left| \begin{array}{c} ((s, h), (s', h')) \in \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}'\right) \epsilon\right) \\ &\wedge v \in \mathrm{VAL} \end{array} \right\} \\ &= \texttt{frame}\left(\left\{ \left((s[x \mapsto v], h), (s'[x \mapsto v], h') \right) \left| \begin{array}{c} ((s, h), (s', h')) \in \texttt{foot}\left(\mathbb{C}'\right) \epsilon \\ &\wedge v \in \mathrm{VAL} \end{array} \right\} \right) \\ &= \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}\right) \epsilon\right) \end{split}$$

 $\mathbf{Case}\ \mathbb{C}=\mathbb{C}_1;\mathbb{C}_2$

$$\forall \epsilon. \ \llbracket \mathbb{C}_1 \rrbracket \epsilon = \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_1\right) \epsilon\right) \land \llbracket \mathbb{C}_2 \rrbracket \epsilon = \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_2\right) \epsilon\right) \qquad (I.H)$$

In what follows we show $\llbracket \mathbb{C} \rrbracket \epsilon \subseteq \operatorname{frame} (\operatorname{foot} (\mathbb{C}) \epsilon)$ and $\operatorname{frame} (\operatorname{foot} (\mathbb{C}) \epsilon) \subseteq \llbracket \mathbb{C} \rrbracket \epsilon$, thus establishing $\llbracket \mathbb{C} \rrbracket \epsilon = \operatorname{frame} (\operatorname{foot} (\mathbb{C}) \epsilon)$, as required.

For the first part, from the definitions of foot (.), frame (.), [.], Lemma 3 and (I.H) we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &\triangleq \left\{ (\sigma, \sigma') \middle| \substack{\epsilon \neq ok \land (\sigma, \sigma') \in \llbracket \mathbb{C}_1 \rrbracket \epsilon} \\ \lor \exists \sigma''. (\sigma, \sigma'') \in \llbracket \mathbb{C}_1 \rrbracket ok \land (\sigma'', \sigma') \in \llbracket \mathbb{C}_2 \rrbracket \epsilon \right\} \\ &= \left\{ (\sigma, \sigma') \middle| \epsilon \neq ok \land (\sigma, \sigma') \in \llbracket \mathbb{C}_1 \rrbracket \epsilon \right\} \\ \cup \left\{ (\sigma, \sigma') \middle| \exists \sigma''. (\sigma, \sigma'') \in \llbracket \mathbb{C}_1 \rrbracket ok \land (\sigma'', \sigma') \in \llbracket \mathbb{C}_2 \rrbracket \epsilon \right\} \\ \stackrel{I.H}{=} \left\{ (\sigma, \sigma') \middle| \epsilon \neq ok \land (\sigma, \sigma') \in \texttt{frame} (\texttt{foot} (\mathbb{C}_1) \epsilon) \right\} \\ \cup \left\{ (\sigma, \sigma') \middle| \exists \sigma''. (\sigma, \sigma'') \in \texttt{frame} (\texttt{foot} (\mathbb{C}_1) ok) \\ \land (\sigma'', \sigma') \in \texttt{frame} (\texttt{foot} (\mathbb{C}_2) \epsilon) \right\} \\ &= \texttt{frame} \left(\left\{ (\sigma_1, \sigma_2) \middle| \epsilon \neq ok \land (\sigma_1, \sigma_2) \in \texttt{foot} (\mathbb{C}_1) \epsilon \right\} \right) \\ \cup \left\{ ((s_1, h_1 \uplus h), (s_2, h_2 \uplus h')) \middle| \begin{array}{l} \exists s'', h_3, h_4. ((s_1, h_1), (s', h_3)) \in \texttt{foot} (\mathbb{C}_1) ok \\ \land (s', h_4), (s_2, h_2) \in \texttt{foot} (\mathbb{C}_2) \epsilon \\ \land h_3 \uplus h = h_4 \uplus h' \end{split} \end{split}$$

A. Raad, J. Berdine, H.-H. Dang, D. Dreyer, P. O'Hearn, and J. Villard

 $(Lemma \ 3) \subseteq \texttt{frame}\left(\left\{\left(\sigma_{1}, \sigma_{2}\right) \,\middle|\, \epsilon \neq ok \land \left(\sigma_{1}, \sigma_{2}\right) \in \texttt{foot}\left(\mathbb{C}_{1}\right) \epsilon\right\}\right)$

$$\begin{array}{l} \bigcup \left\{ \left((s_1, h_1 \uplus h), (s_2, h_2 \uplus h') \right) \left| \begin{array}{l} \exists s'', h_3, h_4. \left((s_1, h_1), (s', h_3) \right) \in \mathsf{foot} (\mathbb{C}_1) \, ok \\ \land \left((s', h_4), (s_2, h_2) \right) \in \mathsf{foot} (\mathbb{C}_2) \, \epsilon \\ \land \exists h_{34}, h_{3b}, h_{a4}, h_{ab}. \\ h_3 = h_{34} \uplus h_{3b} \land h = h_{a4} \uplus h_{ab} \\ \land h_4 = h_{34} \uplus h_{a4} \land h' = h_{3b} \uplus h_{ab} \end{array} \right\} \\ = \mathsf{frame} \left(\left\{ (\sigma_1, \sigma_2) \middle| \epsilon \neq ok \land (\sigma_1, \sigma_2) \in \mathsf{foot} (\mathbb{C}_1) \, \epsilon \right\} \\ \cup \left\{ \left((s_1, h_1 \uplus h_{a4} \uplus h_{ab}), (s_2, h_2 \uplus h_{3b} \uplus h_{ab}) \middle| \begin{array}{l} \exists h_{34}. \left((s_1, h_1), (s', h_{34} \uplus h_{3b}) \right) \in \mathsf{foot} (\mathbb{C}_1) \, ok \\ \land ((s', h_{34} \uplus h_{a4}), (s_2, h_2)) \in \mathsf{foot} (\mathbb{C}_2) \, \epsilon \right\} \\ = \mathsf{frame} \left(\left\{ (\sigma_1, \sigma_2) \middle| \epsilon \neq ok \land (\sigma_1, \sigma_2) \in \mathsf{foot} (\mathbb{C}_1) \, \epsilon \right\} \\ \cup \mathsf{frame} \left(\left\{ ((s_1, h_1 \uplus h_{a4}), (s_2, h_2 \uplus h_{3b}) \right) \middle| \begin{array}{l} \exists h_{34}. \left((s_1, h_1), (s', h_{34} \uplus h_{3b}) \right) \in \mathsf{foot} (\mathbb{C}_1) \, ok \\ \land ((s', h_{34} \uplus h_{a4}), (s_2, h_2)) \in \mathsf{foot} (\mathbb{C}_2) \, \epsilon \right\} \\ = \mathsf{frame} \left(\left\{ (\sigma_1, \sigma_2) \middle| \epsilon \neq ok \land (\sigma_1, \sigma_2) \in \mathsf{foot} (\mathbb{C}_1) \, \epsilon \right\} \\ \cup \left\{ (\sigma_1 \bullet \sigma_{a4}, \sigma_2 \bullet \sigma_{3b}) \middle| \begin{array}{l} \exists \sigma_{34}. (\sigma_1, \sigma_{34} \bullet \sigma_{3b}) \in \mathsf{foot} (\mathbb{C}_1) \, ok \\ \land (\sigma_{34} \bullet \sigma_{a4}, \sigma_2) \in \mathsf{foot} (\mathbb{C}_2) \, \epsilon \right\} \\ = \mathsf{frame} \left(\mathsf{foot} (\mathbb{C}_1; \mathbb{C}_2) \, \epsilon \right) \\ = \mathsf{frame} \left(\mathsf{foot} (\mathbb{C}) \, \epsilon \right) \end{aligned} \right)$$

For the second part, from the definitions of $\texttt{foot}(.),\,\texttt{frame}\,(.),\,[\![.]\!],\,\texttt{Lemma 4}$ and (I.H) we have:

$$\begin{aligned} \text{frame}\left(\text{foot}\left(\mathbb{C}\right)\epsilon\right) &= \left\{ \left((s_{1},h_{1} \uplus h_{r}),(s_{2},h_{2} \uplus h_{r})\right) \middle| \left((s_{1},h_{1}),(s_{2},h_{2})\right) \in \text{foot}\left(\mathbb{C}\right)\epsilon \land h \in \text{HEAP} \right\} \\ &= \left\{ \left((s_{1},h_{1} \uplus h_{r}),(s_{2},h_{2} \uplus h_{r})\right) \middle| \epsilon \neq ok \land \left((s_{1},h_{1}),(s_{2},h_{2})\right) \in \text{foot}\left(\mathbb{C}_{1}\right)\epsilon \right\} \\ &\cup \left\{ \left((s_{1},h_{1} \uplus h \uplus h_{r}),(s_{2},h_{2} \uplus h' \uplus h_{r})\right) \middle| \frac{\exists h_{c},s_{3}.((s_{1},h_{1}),(s_{2},h_{2})) \in \text{foot}\left(\mathbb{C}_{2}\right)\epsilon}{\land \left((s_{3},h_{c} \uplus h),(s_{2},h_{2})\right) \in \text{foot}\left(\mathbb{C}_{2}\right)\epsilon} \right\} \\ &\cup \left\{ \left((s_{1},h_{1} \uplus h_{r}),(s_{2},h_{2} \uplus h_{r})\right) \middle| \epsilon \neq ok \land \left((s_{1},h_{1} \uplus h_{r}),(s_{2},h_{2} \uplus h_{r})\right) \in \left[\mathbb{C}_{1}\right]\epsilon} \right\} \\ &\cup \left\{ \left((s_{1},h_{1} \uplus h \uplus h_{r}),(s_{2},h_{2} \uplus h' \uplus h_{r})\right) \middle| \epsilon \neq ok \land \left((s_{1},h_{1} \uplus h \uplus h_{r}),(s_{2},h_{2} \uplus h_{r})\right) \in \left[\mathbb{C}_{1}\right]\epsilon} \right\} \\ &\cup \left\{ \left((s_{1},h_{1} \uplus h \uplus h_{r}),(s_{2},h_{2} \uplus h' \uplus h_{r})\right) \right| \frac{\exists h_{c},s_{3}}{\land \left((s_{3},h_{c} \uplus h \uplus h_{r}),(s_{3},h' \uplus h_{c} \uplus h \uplus h_{r})) \in \left[\mathbb{C}_{1}\right]ok} \right\} \\ &= \left\{ (\sigma,\sigma') \middle| \epsilon \neq ok \land (\sigma,\sigma') \in \left[\mathbb{C}_{1}\right]\epsilon} \\ &\cup \left\{ (\sigma,\sigma') \middle| \exists \sigma''.(\sigma,\sigma'') \in \left[\mathbb{C}_{1}\right]ek \land (\sigma'',\sigma') \in \left[\mathbb{C}_{2}\right]ek \right\} \\ &= \left\{ (\sigma,\sigma') \middle| \frac{\epsilon \neq ok \land (\sigma,\sigma'') \in \left[\mathbb{C}_{1}\right]ek}{\lor \exists \sigma''.(\sigma,\sigma'') \in \left[\mathbb{C}_{1}\right]ok \land (\sigma'',\sigma') \in \left[\mathbb{C}_{2}\right]ek} \right\} \\ &= \left[\mathbb{C}\right]\epsilon \end{aligned}$$

 $\mathbf{Case}\ \mathbb{C}=\mathbb{C}_1+\mathbb{C}_2$

$$\forall \epsilon. \ \llbracket \mathbb{C}_1 \rrbracket \epsilon = \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_1\right) \epsilon\right) \land \llbracket \mathbb{C}_2 \rrbracket \epsilon = \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_2\right) \epsilon\right) \qquad (I.H)$$

From the definitions of $\texttt{foot}\left(.\right),\,\texttt{frame}\left(.\right),\,\llbracket.\rrbracket$ and $\left(I.H\right)$ we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \llbracket \mathbb{C}_1 \rrbracket \epsilon \cup \llbracket \mathbb{C}_2 \rrbracket \epsilon \\ &= \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}_1\right) \epsilon\right) \cup \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}_2\right) \epsilon\right) \end{split}$$

38

$$= \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_1 + \mathbb{C}_2\right) \epsilon\right)$$
$$= \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}\right) \epsilon\right)$$

Case $\mathbb{C} = \mathbb{C}_r^{\star}$ We first demonstrate that:

$$\forall i \in \mathbb{N}. \ [\![\mathbb{C}_r^i]\!] \epsilon = \texttt{frame}\left(\texttt{foot}\left(\mathbb{C}_r^i\right)\epsilon\right) \tag{1}$$

We proceed by induction on i.

Base case i = 0

It suffices to show that $[skip]\epsilon = frame(foot(skip)\epsilon)$, which follows from the proof of case skip above.

Inductive case i = n+1

From the definition of \mathbb{C}_r^{n+1} we then have $[\![\mathbb{C}_r^{n+1}]\!]\epsilon = [\![\mathbb{C}_r; \mathbb{C}_r^n]\!]\epsilon$. On the other hand, from the proof of the sequential case composition we have $[\![\mathbb{C}_r; \mathbb{C}_r^n]\!]\epsilon =$ frame (foot $(\mathbb{C}_r; \mathbb{C}_r^n)\epsilon$), and thus we have $[\![\mathbb{C}_r^{n+1}]\!]\epsilon =$ frame (foot $(\mathbb{C}_r; \mathbb{C}_r^n)\epsilon$). Finally, from definition of \mathbb{C}_r^{n+1} we have $\mathbb{C}_r; \mathbb{C}_r^n = \mathbb{C}_r^{n+1}$ and thus we have $[\![\mathbb{C}_r^{n+1}]\!]\epsilon =$ frame (foot $(\mathbb{C}_r^{n+1})\epsilon$), as required.

From the definitions of foot (.), frame (.), [.] and (1) we have:

$$\begin{split} \llbracket \mathbb{C} \rrbracket \epsilon &= \bigcup_{i \in \mathbb{N}} \llbracket \mathbb{C}_r^i \rrbracket \epsilon \\ \stackrel{(1)}{=} \bigcup_{i \in \mathbb{N}} \texttt{frame} \left(\texttt{foot} \left(\mathbb{C}_r^i \right) \epsilon \right) \\ &= \texttt{frame} \left(\bigcup_{i \in \mathbb{N}} \texttt{foot} \left(\mathbb{C}_r^i \right) \epsilon \right) \\ &= \texttt{frame} \left(\texttt{foot} \left(\mathbb{C} \right) \epsilon \right) \end{split}$$

40 A. Raad, J. Berdine, H.-H. Dang, D. Dreyer, P. O'Hearn, and J. Villard

D Symbolic Execution Rules

We now list all rules for the analysis described in §5.

SE-SEQ1 $[p] \mathbb{C} [ok:q] \mathbb{C}_i \rightsquigarrow [p_1] \mathbb{C}; \mathbb{C}_1 [\epsilon_1:q_1]$ $\frac{[p_1]\mathbb{C};\mathbb{C}_1[\epsilon_1:q_1]\mathbb{C}_2 \rightsquigarrow [p_2]\mathbb{C};\mathbb{C}_1;\mathbb{C}_2[\epsilon_2:q_2]}{[p]\mathbb{C}[ok:q]\mathbb{C}_1;\mathbb{C}_2 \rightsquigarrow [p_2]\mathbb{C};\mathbb{C}_1;\mathbb{C}_2[\epsilon_2:q_2]}$ SE-Seq2 $[p] \mathbb{C}_1 [er(L): q] \mathbb{C}_2 \rightsquigarrow [p] \mathbb{C}_1; \mathbb{C}_2 [er(L): q]$ SE-LOCAL $\frac{[p[x'/x]] \mathbb{C} [ok:q[x'/x]] \mathbb{C}' \rightsquigarrow [p'] \mathbb{C}; \mathbb{C}' [\epsilon:q']}{x' \notin \mathsf{fv}(p,q,\mathbb{C},\mathbb{C}') \qquad z \notin \mathsf{fv}(p',q',\mathbb{C},\mathbb{C}')}$ $\frac{[p] \mathbb{C} [ok:q] \operatorname{local} x \text{ in } \mathbb{C}' \rightsquigarrow [p'[z/x']] \mathbb{C}; \operatorname{local} x \text{ in } \mathbb{C}' [\epsilon:q'[z/x']]}{[p] \mathbb{C} [ok:q] \operatorname{local} x \text{ in } \mathbb{C}' \rightsquigarrow [p'[z/x']] \mathbb{C}; \operatorname{local} x \text{ in } \mathbb{C}' [\epsilon:q'[z/x']]}$ SE-LOOP $[p] \mathbb{C}' [ok:q]$ skip $+ \mathbb{C} + (\mathbb{C};\mathbb{C}) + \cdots + \mathbb{C}^{N_{loops}}$ $\rightsquigarrow [p'] \mathbb{C}'; \text{skip} + \mathbb{C} + (\mathbb{C}; \mathbb{C}) + \dots + \mathbb{C}^{N_{loops}} [\epsilon : q']$ $[p] \mathbb{C}' [ok:q] \mathbb{C}^{\star} \rightsquigarrow [p'] \mathbb{C}'; \mathbb{C}^{\star} [\epsilon:q']$ $\frac{[p] \subset [one 1]}{[p] C [ok: q] C_i \rightsquigarrow [p_i] C; C_i [\epsilon_i : q_i]}$ $\frac{[p] C [ok: q] C_i \rightsquigarrow [p_i] C; C_i [\epsilon_i : q_i]}{[p] C [ok: q] C_1 + C_2 \rightsquigarrow [p_i] C; C_1 + C_2 [\epsilon_i : q_i]}$ $[p] \mathbb{C} [ok:q] \text{ skip } \rightsquigarrow [p] \mathbb{C}; \text{ skip } [ok:q]$ SE-Error $[p] \mathbb{C} [ok:q]$ L: error $\rightsquigarrow [p] \mathbb{C}$; L: error [er(L):q]SE-Assign $\frac{x' \notin \mathsf{fv}(p, \mathbb{C}, x, e, q)}{[p] \mathbb{C} [ok:q] \ x := e \rightsquigarrow [p] \mathbb{C}; x := e [ok:x = e[x'/x] * q[x'/x]]}$ SE-HAVOC $\frac{x' \notin \mathsf{fv}(p, \mathbb{C}, x, q)}{[p] \mathbb{C} [ok:q] \ x := * \rightsquigarrow [p] \mathbb{C}; x := * [ok:q[x'/x]]}$ SE-Assume $[p] \mathbb{C}[ok:q]$ assume(B) $\rightsquigarrow [p] \mathbb{C}$; assume(B) [ok:B*q]

Note that SE-Assume does not require B * q to be explicitly satisfiable. This is because we implicitly stop the symbolic execution any time either the inferred presumption or current state becomes inconsistent due to the application of any rule.

$$\begin{split} & \underset{[p] \ \mathbb{C} \ [ok:q] \ x := \texttt{alloc}(\texttt{)} \ \rightsquigarrow \ [p] \ \mathbb{C}; x := \texttt{alloc}(\texttt{)} \ [ok:q[x'/x] * x \mapsto v] \end{split}$$

There is no rule corresponding to ALLOC2 in our analysis. This is not a fundamental choice but rather a practical one, as including such a rule would introduce branching on all known invalidated addresses at each alloc() call site, which can blow up the exploration space. To put it another way, we could easily include

an analogue of SE-ALLOC1 for re-using known-invalidated addresses; the ability not to do so is granted to us by the under-approximate setting.

SE-LOAD